

Exercise 1 *Orthonormal basis and measurement principle*

1) It involves the following checking:

$$\begin{aligned} \langle \alpha | \alpha \rangle &= (\cos \alpha \langle x | + \sin \alpha \langle y |) (\cos \alpha |x\rangle + \sin \alpha |y\rangle) \\ &= \cos^2 \alpha + \sin^2 \alpha = 1 \\ \langle \alpha_{\perp} | \alpha_{\perp} \rangle &= (-\sin \alpha \langle x | + \cos \alpha \langle y |) (-\sin \alpha |x\rangle + \cos \alpha |y\rangle) \\ &= \cos^2 \alpha + \sin^2 \alpha = 1 \\ \langle \alpha_{\perp} | \alpha \rangle &= (-\sin \alpha \langle x | + \cos \alpha \langle y |) (\cos \alpha |x\rangle + \sin \alpha |y\rangle) \\ &= -\sin \alpha \cos \alpha + \cos \alpha \sin \alpha = 0 \\ \\ \langle R | R \rangle &= \frac{1}{2} (\langle x | - i \langle y |) (|x\rangle + i |y\rangle) = \frac{1}{2} (1^2 + (-i)i) = 1 \\ \langle L | L \rangle &= \frac{1}{2} (\langle x | + i \langle y |) (|x\rangle - i |y\rangle) = \frac{1}{2} (1^2 + i(-i)) = 1 \\ \langle R | L \rangle &= \frac{1}{2} (\langle x | - i \langle y |) (|x\rangle - i |y\rangle) = \frac{1}{2} (1^2 + (-i)(-i)) = 0 \end{aligned}$$

2) For each experiment, the possible states just after the measurement would be the corresponding measurement basis with the following probabilities:

$$\begin{aligned} \text{Prob}(|x\rangle) &= |\langle x | \psi \rangle|^2 = \cos^2 \theta \\ \text{Prob}(|y\rangle) &= |\langle y | \psi \rangle|^2 = |(\sin \theta) e^{i\varphi}|^2 = \sin^2 \theta \end{aligned}$$

where we use $e^{i\varphi} = \cos \varphi + i \sin \varphi$ so that $|e^{i\varphi}|^2 = \cos^2 \varphi + \sin^2 \varphi = 1$. For the other probabilities we have:

$$\begin{aligned} \text{Prob}(|R\rangle) &= |\langle R | \psi \rangle|^2 \\ &= \left| \frac{1}{\sqrt{2}} (\langle x | - i \langle y |) (\cos \theta |x\rangle + (\sin \theta) e^{i\varphi} |y\rangle) \right|^2 \\ &= \left| \frac{1}{\sqrt{2}} \cos \theta - \frac{1}{\sqrt{2}} i \sin \theta e^{i\varphi} \right|^2 \\ &= \left| \frac{1}{\sqrt{2}} \cos \theta + \frac{1}{\sqrt{2}} \sin \theta \sin \varphi - \frac{1}{\sqrt{2}} i \sin \theta \cos \varphi \right|^2 \\ &= \left(\frac{1}{\sqrt{2}} \cos \theta + \frac{1}{\sqrt{2}} \sin \theta \sin \varphi \right)^2 + \left(\frac{1}{\sqrt{2}} \sin \theta \cos \varphi \right)^2 \\ &= \frac{1}{2} + \cos \theta \sin \theta \sin \varphi \end{aligned}$$

$$\begin{aligned}
\text{Prob}(|L\rangle) &= |\langle L|\psi\rangle|^2 \\
&= \left| \frac{1}{\sqrt{2}} (\langle x| + i\langle y|) (\cos\theta|x\rangle + (\sin\theta)e^{i\varphi}|y\rangle) \right|^2 \\
&= \left| \frac{1}{\sqrt{2}} \cos\theta + \frac{1}{\sqrt{2}} i \sin\theta e^{i\varphi} \right|^2 \\
&= \left| \frac{1}{\sqrt{2}} \cos\theta - \frac{1}{\sqrt{2}} \sin\theta \sin\varphi + \frac{1}{\sqrt{2}} i \sin\theta \cos\varphi \right|^2 \\
&= \left(\frac{1}{\sqrt{2}} \cos\theta - \frac{1}{\sqrt{2}} \sin\theta \sin\varphi \right)^2 + \left(\frac{1}{\sqrt{2}} \sin\theta \cos\varphi \right)^2 \\
&= \frac{1}{2} - \cos\theta \sin\theta \sin\varphi
\end{aligned}$$

$$\begin{aligned}
\text{Prob}(|\alpha\rangle) &= |\langle \alpha|\psi\rangle|^2 \\
&= |(\cos\alpha\langle x| + \sin\alpha\langle y|) (\cos\theta|x\rangle + (\sin\theta)e^{i\varphi}|y\rangle)|^2 \\
&= |\cos\alpha\cos\theta + \sin\alpha\sin\theta e^{i\varphi}|^2 \\
&= |\cos\alpha\cos\theta + \sin\alpha\sin\theta\cos\varphi + i\sin\alpha\sin\theta\sin\varphi|^2 \\
&= (\cos\alpha\cos\theta + \sin\alpha\sin\theta\cos\varphi)^2 + (\sin\alpha\sin\theta\sin\varphi)^2 \\
&= \cos^2\alpha\cos^2\theta + 2\cos\alpha\sin\alpha\cos\theta\sin\theta\cos\varphi + \sin^2\alpha\sin^2\theta
\end{aligned}$$

$$\begin{aligned}
\text{Prob}(|\alpha_\perp\rangle) &= |\langle \alpha_\perp|\psi\rangle|^2 \\
&= |(\sin\alpha\langle x| + \cos\alpha\langle y|) (\cos\theta|x\rangle + (\sin\theta)e^{i\varphi}|y\rangle)|^2 \\
&= |-\sin\alpha\cos\theta + \cos\alpha\sin\theta e^{i\varphi}|^2 \\
&= |-\sin\alpha\cos\theta + \cos\alpha\sin\theta\cos\varphi + i\cos\alpha\sin\theta\sin\varphi|^2 \\
&= (\sin\alpha\cos\theta - \cos\alpha\sin\theta\cos\varphi)^2 + (\cos\alpha\sin\theta\sin\varphi)^2 \\
&= \sin^2\alpha\cos^2\theta - 2\cos\alpha\sin\alpha\cos\theta\sin\theta\cos\varphi + \cos^2\alpha\sin^2\theta
\end{aligned}$$

One can verify that these probabilities are normalized to one,

$$\text{Prob}(|x\rangle) + \text{Prob}(|y\rangle) = \text{Prob}(|R\rangle) + \text{Prob}(|L\rangle) = \text{Prob}(|\alpha\rangle) + \text{Prob}(|\alpha_\perp\rangle) = 1.$$

Exercise 2 Matrices in Dirac's notation

1) As $\{|x\rangle, |y\rangle\}$ is a set of orthonormal basis, we have

$$\begin{aligned}
(\gamma^*\langle x| + \delta^*\langle y|)(\alpha|x\rangle + \beta|y\rangle) &= \gamma^*\alpha\langle x|x\rangle + \gamma^*\beta\langle x|y\rangle + \delta^*\alpha\langle y|x\rangle + \delta^*\beta\langle y|y\rangle \\
&= \gamma^*\alpha + \delta^*\beta.
\end{aligned}$$

2)

$$\begin{aligned}
& (\alpha |x\rangle + \beta |y\rangle)(\gamma^* \langle x| + \delta^* \langle y|) \\
&= \alpha\gamma^* |x\rangle \langle x| + \alpha\delta^* |x\rangle \langle y| + \beta\gamma^* |y\rangle \langle x| + \beta\delta^* |y\rangle \langle y| \\
&= \alpha\gamma^* \begin{pmatrix} 1 \\ 0 \end{pmatrix} (1 \ 0) + \alpha\delta^* \begin{pmatrix} 1 \\ 0 \end{pmatrix} (0 \ 1) + \beta\gamma^* \begin{pmatrix} 0 \\ 1 \end{pmatrix} (1 \ 0) + \beta\delta^* \begin{pmatrix} 0 \\ 1 \end{pmatrix} (0 \ 1) \\
&= \begin{pmatrix} \alpha\gamma^* & \alpha\delta^* \\ \beta\gamma^* & \beta\delta^* \end{pmatrix}
\end{aligned}$$

3)

$$\begin{aligned}
A &= \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \\
&= a_{11} \begin{pmatrix} 1 \\ 0 \end{pmatrix} (1 \ 0) + a_{12} \begin{pmatrix} 1 \\ 0 \end{pmatrix} (0 \ 1) + a_{21} \begin{pmatrix} 0 \\ 1 \end{pmatrix} (1 \ 0) + a_{22} \begin{pmatrix} 0 \\ 1 \end{pmatrix} (0 \ 1) \\
&= a_{11} |x\rangle \langle x| + a_{12} |x\rangle \langle y| + a_{21} |y\rangle \langle x| + a_{22} |y\rangle \langle y|
\end{aligned}$$

4) As

$$\begin{aligned}
|\alpha\rangle &= \cos \alpha |x\rangle + \sin \alpha |y\rangle, \\
|\alpha_\perp\rangle &= -\sin \alpha |x\rangle + \cos \alpha |y\rangle,
\end{aligned}$$

we find $|x\rangle, |y\rangle$ by linear combination of the above two equations:

$$\begin{aligned}
\cos \alpha |\alpha\rangle - \sin \alpha |\alpha_\perp\rangle &= (\cos^2 \alpha + \sin^2 \alpha) |x\rangle = |x\rangle, \\
\sin \alpha |\alpha\rangle + \cos \alpha |\alpha_\perp\rangle &= (\sin^2 \alpha + \cos^2 \alpha) |y\rangle = |y\rangle.
\end{aligned}$$

Then we have

$$\begin{aligned}
|x\rangle \langle x| &= (\cos \alpha |\alpha\rangle - \sin \alpha |\alpha_\perp\rangle)(\cos \alpha \langle \alpha| - \sin \alpha \langle \alpha_\perp|) \\
&= \cos^2 \alpha |\alpha\rangle \langle \alpha| - \sin \alpha \cos \alpha |\alpha\rangle \langle \alpha_\perp| - \sin \alpha \cos \alpha |\alpha_\perp\rangle \langle \alpha| + \sin^2 \alpha |\alpha_\perp\rangle \langle \alpha_\perp|, \\
|x\rangle \langle y| &= (\cos \alpha |\alpha\rangle - \sin \alpha |\alpha_\perp\rangle)(\sin \alpha \langle \alpha| + \cos \alpha \langle \alpha_\perp|) \\
&= \sin \alpha \cos \alpha |\alpha\rangle \langle \alpha| + \cos^2 \alpha |\alpha\rangle \langle \alpha_\perp| - \sin^2 \alpha |\alpha_\perp\rangle \langle \alpha| - \sin \alpha \cos \alpha |\alpha_\perp\rangle \langle \alpha_\perp|, \\
|y\rangle \langle x| &= (\sin \alpha |\alpha\rangle + \cos \alpha |\alpha_\perp\rangle)(\cos \alpha \langle \alpha| - \sin \alpha \langle \alpha_\perp|) \\
&= \sin \alpha \cos \alpha |\alpha\rangle \langle \alpha| - \sin^2 \alpha |\alpha\rangle \langle \alpha_\perp| + \cos^2 \alpha |\alpha_\perp\rangle \langle \alpha| - \sin \alpha \cos \alpha |\alpha_\perp\rangle \langle \alpha_\perp|, \\
|y\rangle \langle y| &= (\sin \alpha |\alpha\rangle + \cos \alpha |\alpha_\perp\rangle)(\sin \alpha \langle \alpha| + \cos \alpha \langle \alpha_\perp|) \\
&= \sin^2 \alpha |\alpha\rangle \langle \alpha| + \sin \alpha \cos \alpha |\alpha\rangle \langle \alpha_\perp| + \sin \alpha \cos \alpha |\alpha_\perp\rangle \langle \alpha| + \cos^2 \alpha |\alpha_\perp\rangle \langle \alpha_\perp|.
\end{aligned}$$

Substituting all these into A , we have

$$\begin{aligned}
A &= a_{11} |x\rangle \langle x| + a_{12} |x\rangle \langle y| + a_{21} |y\rangle \langle x| + a_{22} |y\rangle \langle y| \\
&= (a_{11} \cos^2 \alpha + a_{12} \sin \alpha \cos \alpha + a_{21} \sin \alpha \cos \alpha + a_{22} \sin^2 \alpha) |\alpha\rangle \langle \alpha| \\
&\quad + (-a_{11} \sin \alpha \cos \alpha + a_{12} \cos^2 \alpha - a_{21} \sin^2 \alpha + a_{22} \sin \alpha \cos \alpha) |\alpha\rangle \langle \alpha_\perp| \\
&\quad + (-a_{11} \sin \alpha \cos \alpha - a_{12} \sin^2 \alpha + a_{21} \cos^2 \alpha + a_{22} \sin \alpha \cos \alpha) |\alpha_\perp\rangle \langle \alpha| \\
&\quad + (+a_{11} \sin^2 \alpha - a_{12} \sin \alpha \cos \alpha - a_{21} \sin \alpha \cos \alpha + a_{22} \cos^2 \alpha) |\alpha_\perp\rangle \langle \alpha_\perp|.
\end{aligned}$$

Therefore, we have

$$\begin{aligned}\tilde{a}_{11} &= a_{11} \cos^2 \alpha + a_{12} \sin \alpha \cos \alpha + a_{21} \sin \alpha \cos \alpha + a_{22} \sin^2 \alpha, \\ \tilde{a}_{12} &= -a_{11} \sin \alpha \cos \alpha + a_{12} \cos^2 \alpha - a_{21} \sin^2 \alpha + a_{22} \sin \alpha \cos \alpha, \\ \tilde{a}_{21} &= a_{11} \sin \alpha \cos \alpha - a_{12} \sin^2 \alpha + a_{21} \cos^2 \alpha + a_{22} \sin \alpha \cos \alpha, \\ \tilde{a}_{22} &= a_{11} \sin^2 \alpha - a_{12} \sin \alpha \cos \alpha - a_{21} \sin \alpha \cos \alpha + a_{22} \cos^2 \alpha.\end{aligned}$$

An alternative approach to find $\tilde{a}_{11}, \tilde{a}_{12}, \tilde{a}_{21}, \tilde{a}_{22}$:

Suppose we replace the matrix notations by $|\alpha\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}$ and $|\alpha_\perp\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ such that $|x\rangle = \cos \alpha |\alpha\rangle - \sin \alpha |\alpha_\perp\rangle = \begin{pmatrix} \cos \alpha \\ -\sin \alpha \end{pmatrix}$ and $|y\rangle = \sin \alpha |\alpha\rangle + \cos \alpha |\alpha_\perp\rangle = \begin{pmatrix} \sin \alpha \\ \cos \alpha \end{pmatrix}$. Consider the equation

$$\begin{aligned}\tilde{a}_{11} |\alpha\rangle \langle \alpha| + \tilde{a}_{12} |\alpha\rangle \langle \alpha_\perp| + \tilde{a}_{21} |\alpha_\perp\rangle \langle \alpha| + \tilde{a}_{22} |\alpha_\perp\rangle \langle \alpha_\perp| \\ = a_{11} |x\rangle \langle x| + a_{12} |x\rangle \langle y| + a_{21} |y\rangle \langle x| + a_{22} |y\rangle \langle y|.\end{aligned}$$

In the $\{|\alpha\rangle, |\alpha_\perp\rangle\}$ basis, the L.H.S. equals $\begin{pmatrix} \tilde{a}_{11} & \tilde{a}_{12} \\ \tilde{a}_{21} & \tilde{a}_{22} \end{pmatrix}$ and the R.H.S. equals

$$\begin{aligned}a_{11} \begin{pmatrix} \cos \alpha \\ -\sin \alpha \end{pmatrix} (\cos \alpha \quad -\sin \alpha) + a_{12} \begin{pmatrix} \cos \alpha \\ -\sin \alpha \end{pmatrix} (\sin \alpha \quad \cos \alpha) \\ + a_{21} \begin{pmatrix} \sin \alpha \\ \cos \alpha \end{pmatrix} (\cos \alpha \quad -\sin \alpha) + a_{22} \begin{pmatrix} \sin \alpha \\ \cos \alpha \end{pmatrix} (\sin \alpha \quad \cos \alpha) \\ = \begin{pmatrix} \cos \alpha \\ -\sin \alpha \end{pmatrix} (a_{11} \quad a_{12}) \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} + \begin{pmatrix} \sin \alpha \\ \cos \alpha \end{pmatrix} (a_{21} \quad a_{22}) \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} \\ = \begin{pmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{pmatrix} \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} \cos \alpha & -\sin \alpha \\ \sin \alpha & \cos \alpha \end{pmatrix} \\ = P \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} P^{-1}\end{aligned}$$

where $P = \begin{pmatrix} \cos \alpha & \sin \alpha \\ -\sin \alpha & \cos \alpha \end{pmatrix}$. Therefore we find that the usual basis transformation rule

$$\begin{pmatrix} \tilde{a}_{11} & \tilde{a}_{12} \\ \tilde{a}_{21} & \tilde{a}_{22} \end{pmatrix} = P \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} P^{-1}$$

Exercise 3 Interferometer revisited

1) Using Exercise 2.3, we have

$$\begin{aligned}S &= |H\rangle \langle H| + i |H\rangle \langle V| + i |V\rangle \langle H| + |V\rangle \langle V| \\ R &= i |H\rangle \langle V| + i |V\rangle \langle H|.\end{aligned}$$

2) The computation in Dirac's notation is

$$\begin{aligned}RS &= \frac{1}{\sqrt{2}} (-|H\rangle \langle H| + i |H\rangle \langle V| + i |V\rangle \langle H| - |V\rangle \langle V|), \\ SRS &= -|H\rangle \langle H| - |V\rangle \langle V|.\end{aligned}$$

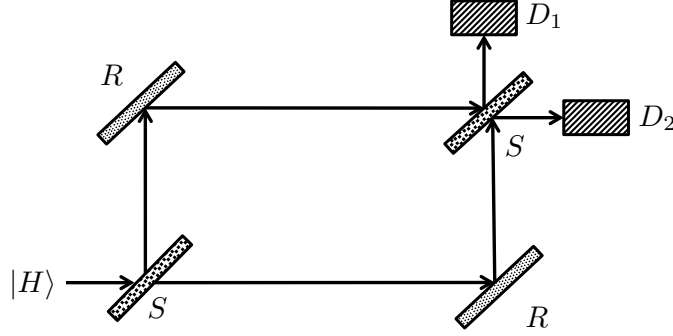
The computation in usual matrix notation is

$$SRS = \frac{1}{2} \begin{pmatrix} 1 & i \\ i & 1 \end{pmatrix} \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} \begin{pmatrix} 1 & i \\ i & 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} 1 & i \\ i & 1 \end{pmatrix} \begin{pmatrix} -1 & i \\ i & -1 \end{pmatrix} = \begin{pmatrix} -1 & 0 \\ 0 & -1 \end{pmatrix}.$$

3)

$$\begin{aligned} SRS |H\rangle &= (-|H\rangle \langle H| - |V\rangle \langle V|) |H\rangle = -|H\rangle \\ |\langle H | SRS |H\rangle|^2 &= |-\langle H|H\rangle|^2 = 1 \\ |\langle V | SRS |H\rangle|^2 &= |-\langle V|H\rangle|^2 = 0 \end{aligned}$$

The experimental set-up:



4) We have

$$SRDS = \frac{1}{2} \begin{pmatrix} 1 & i \\ i & 1 \end{pmatrix} \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix} \begin{pmatrix} e^{i\varphi_1} & 0 \\ 0 & e^{i\varphi_2} \end{pmatrix} \begin{pmatrix} 1 & i \\ i & 1 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -e^{i\varphi_1} - e^{i\varphi_2} & -ie^{i\varphi_1} + ie^{i\varphi_2} \\ ie^{i\varphi_1} - ie^{i\varphi_2} & -e^{i\varphi_1} - e^{i\varphi_2} \end{pmatrix}$$

and

$$SRDS |H\rangle = \frac{1}{2} \begin{pmatrix} -e^{i\varphi_1} - e^{i\varphi_2} \\ ie^{i\varphi_1} - ie^{i\varphi_2} \end{pmatrix},$$

which in Dirac notation is

$$SRDS |H\rangle = -\frac{e^{i\varphi_1} + e^{i\varphi_2}}{2} |H\rangle + \frac{ie^{i\varphi_1} - ie^{i\varphi_2}}{2} |V\rangle.$$

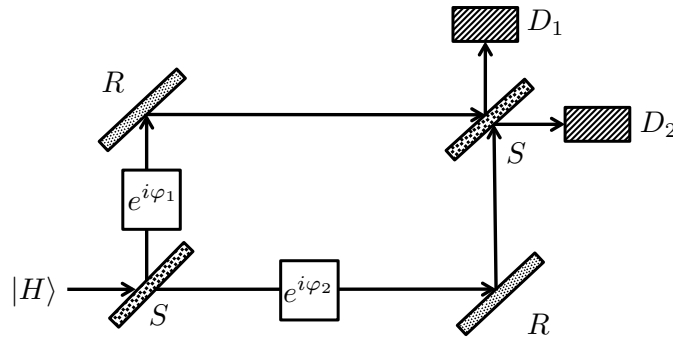
Then we have

$$\begin{aligned} |\langle H | SRDS |H\rangle|^2 &= \left| \frac{e^{i\varphi_1} + e^{i\varphi_2}}{2} \right|^2 \\ &= \frac{1}{4} |\cos \varphi_1 + i \sin \varphi_1 + \cos \varphi_2 + i \sin \varphi_2|^2 \\ &= \frac{1}{4} ((\cos \varphi_1 + \cos \varphi_2)^2 + (\sin \varphi_1 + \sin \varphi_2)^2) \\ &= \frac{1}{4} (2 + 2 \cos \varphi_1 \cos \varphi_2 + 2 \sin \varphi_1 \sin \varphi_2) \\ &= \frac{1}{2} (1 + \cos(\varphi_1 - \varphi_2)) \\ &= \cos^2 \left(\frac{\varphi_1 - \varphi_2}{2} \right) \end{aligned}$$

and

$$\begin{aligned}
|\langle V|SRDS|H\rangle|^2 &= \left| \frac{ie^{i\varphi_1} - ie^{i\varphi_2}}{2} \right|^2 \\
&= \frac{1}{4} |-\sin\varphi_1 + i\cos\varphi_1 + \sin\varphi_1 - i\cos\varphi_2|^2 \\
&= \frac{1}{4} ((\sin\varphi_1 - \sin\varphi_2)^2 + (\cos\varphi_1 - \cos\varphi_2)^2) \\
&= \frac{1}{4} (2 - 2\cos\varphi_1\cos\varphi_2 - 2\sin\varphi_1\sin\varphi_2) \\
&= \frac{1}{2} (1 - \cos(\varphi_1 - \varphi_2)) \\
&= \sin^2\left(\frac{\varphi_1 - \varphi_2}{2}\right)
\end{aligned}$$

The experimental set-up:



A proof that $SRDS$ is unitary: Recall the notation $A^\dagger = A^{\text{T},*}$. We have checked that $SS^\dagger = S^\dagger S = I$ and $RR^\dagger = R^\dagger R = I$ in Homework 2. It is also easy to check $DD^\dagger = D^\dagger D = I$. The product of unitary matrices is unitary, indeed

$$(U_1 U_2)(U_1 U_2)^\dagger = U_1 U_2 U_2^\dagger U_1^\dagger = U_1 U_1^\dagger = I.$$

Remarks: The matrix elements are $\begin{pmatrix} \langle H|SRDS|H\rangle & \langle H|SRDS|V\rangle \\ \langle V|SRDS|H\rangle & \langle V|SRDS|V\rangle \end{pmatrix}$.

- We saw that for a unitary matrix the sum of the modulus squares of rows or columns equal 1. For example for the first column we have $|\langle H|SRDS|H\rangle|^2 + |\langle V|SRDS|H\rangle|^2 = 1$. This expresses the fact that the two probabilities of finding the photon in state $\langle H|$ or $\langle V|$ after the measurement is 1.
- Similarly if we would do an experiment with a photon coming in state $|V\rangle$ when it enters the interferometer, the probabilities of finding it in state $\langle H|$ or $\langle V|$ at the detectors should sum to 1. This means $|\langle H|SRDS|V\rangle|^2 + |\langle V|SRDS|V\rangle|^2 = 1$ which is the sum of the modulus squares of the second column.
- In fact for each of the sum of columns (or rows) that sums to 1, there is an experimental interpretation.