

PROBLEM 1. Suppose we have a linear time invariant channel, i.e.,

$$Y(D) = Q(D)X(D) + Z(D);$$

with $Q(D) = Q^*(D^{-*})$. Also there is another process $U(D) = H(D)X(D)$; which we want to estimate.

(a) Given observations $\{y_k\}$, find the linear estimator

$$\hat{U}(D) = W(D)Y(D)$$

which minimizes the mean-squared error, i.e.,

$$W(D) = \operatorname{argmin}_{W(D)} E\|u_k - \hat{u}_k\|^2$$

You can assume that $\{X_k\}$ and $\{Z_k\}$ are independent and that

$$S_x(D) = E_x$$

and

$$S_z(D) = N_0Q(D).$$

(b) Given the optimum linear MMSE estimator given in part (a) we define the error as

$$e_k = u_k - \hat{u}_k$$

Find the power spectral density of $\{e_k\}$, $S_E(D)$.

(c) If $H(D) = 1$, can you comment on the operation performed in part (a)?

PROBLEM 2. Consider estimating the real zero-mean scalar x from:

$$\mathbf{y} = \mathbf{h}x + \mathbf{w}$$

where $\mathbf{w} \sim \mathcal{N}(0, \frac{N_0}{2}\mathbf{I})$ is uncorrelated with x and \mathbf{h} is a fixed vector in \mathcal{R}^n .

(a) Consider the scaled linear estimate $\mathbf{c}^t\mathbf{y}$ (with the normalization $\|\mathbf{c}\| = 1$):

$$\hat{x} = \mathbf{a}\mathbf{c}^t\mathbf{y} = (\mathbf{a}\mathbf{c}^t\mathbf{h})x + \mathbf{a}\mathbf{c}^t\mathbf{z} \tag{1}$$

Show that the constant a that minimizes the mean square error $(x - \hat{x})^2$ is equal to

$$\frac{\mathbb{E}[x^2]|\mathbf{c}^t\mathbf{h}|}{\mathbb{E}[x^2]|\mathbf{c}^t\mathbf{h}|^2 + \frac{N_0}{2}} \tag{2}$$

- (b) Calculate the minimal mean square error (denoted by MMSE) of the linear estimate in (1) (by using the value of a in (2)). Show that

$$\frac{\mathbb{E}[x^2]}{\text{MMSE}} = 1 + \text{SNR} = 1 + \frac{\mathbb{E}[x^2]|\mathbf{c}^t \mathbf{h}|^2}{\frac{N_0}{2}} \quad (3)$$

For every fixed linear estimator \mathbf{c} , this shows the relationship between the corresponding SNR and MMSE (of an appropriately scaled estimate).

- (c) In particular, relation (3) holds when we optimize over all \mathbf{c} leading to the best linear estimator. Find the value of vector \mathbf{c} (with the normalization $\|\mathbf{c}\| = 1$) by minimizing the MMSE derived in part (b). Compute optimal MMSE.

Hint. Use Cauchy-Schwarz inequality.

PROBLEM 3. (Linear Estimation) Consider the additive noise model given below,

$$Y_1 = X + Z_1$$

$$Y_2 = X + Z_2$$

Let $X, Y_1, Y_2, Z_1, Z_2 \in \mathcal{C}$, i.e. they are complex random variables. Moreover, assume X, Z_1 and Z_2 are zero mean and Z_1 and Z_2 are independent of X .

- (a) Assume the following: $\mathbb{E}[|X|^2] = \mathcal{E}_x$, $\mathbb{E}[|Z_1|^2] = \mathbb{E}[|Z_2|^2] = 1$ and $\mathbb{E}[Z_1 Z_2^*] = 0$. Given Y_1, Y_2 find the best minimum mean squared error linear estimator \hat{X} , where the optimization criterion is $\mathbb{E}[|X - \hat{X}|^2]$.
- (b) If $\mathbb{E}[Z_1 Z_2^*] = \frac{1}{\sqrt{2}}$, what is the best MMSE linear estimator of X ?
- (c) If $\mathbb{E}[Z_1 Z_2^*] = 1$, what is the best MMSE linear estimator of X ?

PROBLEM 4. Let Y_a and Y_b be two separate observations of a zero mean random variable X such that

$$\begin{aligned} Y_a &= H_a X + V_a \\ \text{and } Y_b &= H_b X + V_b, \end{aligned}$$

where $\{V_a, V_b, X\}$ are mutually independent and zero-mean random variables, and $V_a, V_b, X, Y_a, Y_b \in \mathcal{C}$.

- (a) Let \hat{X}_a and \hat{X}_b denote the linear MMSE estimators for X given Y_a and Y_b respectively. That is

$$\begin{aligned} W_a &= \operatorname{argmin}_{W_a} \mathbb{E}[|X - W_a Y_a|^2], \\ W_b &= \operatorname{argmin}_{W_b} \mathbb{E}[|X - W_b Y_b|^2] \end{aligned}$$

and

$$\hat{X}_a = W_a Y_a \quad \text{and} \quad \hat{X}_b = W_b Y_b.$$

Find \hat{X}_a and \hat{X}_b given that

$$\mathbb{E}[X X^*] = \sigma_x^2, \quad \mathbb{E}[V_a V_a^*] = \sigma_a^2, \quad \mathbb{E}[V_b V_b^*] = \sigma_b^2.$$

Also, find the error variances,

$$\begin{aligned} P_a &= \mathbb{E}[(X - \hat{X}_a)(X - \hat{X}_a)^*] \\ P_b &= \mathbb{E}[(X - \hat{X}_b)(X - \hat{X}_b)^*] \end{aligned}$$

(b) We have the following identities,

$$\begin{aligned}\mathbf{R}_x \mathbf{H}^* [\mathbf{H} \mathbf{R}_x \mathbf{H}^* + \mathbf{R}_v]^{-1} &= [\mathbf{R}_x^{-1} + \mathbf{H}^* \mathbf{R}_v^{-1} \mathbf{H}]^{-1} \mathbf{H}^* \mathbf{R}_v^{-1} \\ \mathbf{R}_x - \mathbf{R}_x \mathbf{H}^* [\mathbf{H} \mathbf{R}_x \mathbf{H}^* + \mathbf{R}_v]^{-1} \mathbf{H} \mathbf{R}_x &= [\mathbf{R}_x^{-1} + \mathbf{H}^* \mathbf{R}_v^{-1} \mathbf{H}]^{-1}\end{aligned}$$

where

$$\mathbf{H} = \begin{bmatrix} H_a \\ H_b \end{bmatrix}, \mathbf{R}_v = \begin{bmatrix} \sigma_a^2 & 0 \\ 0 & \sigma_b^2 \end{bmatrix}, \mathbf{R}_x = \sigma_x^2.$$

Prove that

$$P_a^{-1} \hat{X}_a = \frac{H_a^*}{\sigma_a^2} Y_a, \quad P_b^{-1} \hat{X}_b = \frac{H_b^*}{\sigma_b^2} Y_b. \quad (4)$$

and

$$P_a^{-1} = \frac{1}{\sigma_x^2} + \frac{H_a H_a^*}{\sigma_a^2}, \quad P_b^{-1} = \frac{1}{\sigma_x^2} + \frac{H_b H_b^*}{\sigma_b^2}. \quad (5)$$

(c) Now we find the estimator \hat{X} , given both observations Y_a and Y_b , i.e.,

$$\begin{pmatrix} Y_a \\ Y_b \end{pmatrix} = \begin{pmatrix} H_a \\ H_b \end{pmatrix} X + \begin{pmatrix} V_a \\ V_b \end{pmatrix}.$$

We want to find the linear MMSE estimate

$$\hat{X} = (U_a \ U_b) \begin{pmatrix} Y_a \\ Y_b \end{pmatrix},$$

where

$$(U_a \ U_b) = \operatorname{argmin}_{(U_a, U_b)} \mathbb{E}[|X - \hat{X}|^2]$$

and define the corresponding error variance

$$P = \mathbb{E}[(X - \hat{X})(X - \hat{X})^*].$$

Use (4), (5) to show that

$$\begin{aligned}P^{-1} \hat{X} &= P_a^{-1} \hat{X}_a + P_b^{-1} \hat{X}_b \\ \text{and } P^{-1} &= P_a^{-1} + P_b^{-1} - \frac{1}{\sigma_x^2}.\end{aligned}$$