

PROBLEM 1. We wish to use the Kaiser window method to design a discrete-time filter with generalized linear phase that meets specifications of the following form :

$$\begin{aligned} |H(e^{j\omega})| &\leq 0.01, & 0 \leq |\omega| \leq 0.25\pi \\ 0.95 \leq |H(e^{j\omega})| &\leq 1.05, & 0.35\pi \leq |\omega| \leq 0.6\pi \\ |H(e^{j\omega})| &\leq 0.01, & 0.65\pi \leq |\omega| \leq \pi \end{aligned}$$

- Determine the minimum length  $(M + 1)$  of the impulse response and the value of the Kaiser window parameter  $\beta$  for a filter that meets the preceding specifications.
- What is the delay of the filter?
- Determine the ideal impulse response  $h_d[n]$  to which the Kaiser window should be applied.
- Plot the Fourier transform of  $h[n] = h_d[n]w[n]$ .

*Hint.*

[http://en.wikipedia.org/wiki/Window\\_function](http://en.wikipedia.org/wiki/Window_function)

PROBLEM 2. We decide to design a Type I  $M$ -tap FIR filter. We require the filter to be lowpass, with a transition band from  $\omega_p = 0.4\pi$  to  $\omega_s = 0.6\pi$ ; we further state that the tolerances for the realized filters magnitude must not exceed 10 percent in the passband and 1 percent in the stopband.

- Estimate the minimum length  $M$  of the impulse response using Kaiser's formula.
- Use Matlab and run the Parks-McClellan algorithm to find the filter. Check that the filter satisfies the design specification, and if not, increase the number of taps.

PROBLEM 3. Design a FIR bandpass filter using Kaiser's window which passes frequencies between  $0.4\pi$  and  $0.6\pi$  , allowing transition bands from  $0.3\pi, 0.4\pi$  and  $0.6\pi, 0.8\pi$  (i.e., the stopbands are  $0, 0.3\pi$  and  $0.8\pi, \pi$ ). The desired stop-band attenuation is 80 dB, and the passband ripple is required to be no greater than 0.1 dB.

*Hint.* Use `kaiserord` and `fir1` commands.