## ÉCOLE POLYTECHNIQUE FÉDÉRALE DE LAUSANNE

School of Computer and Communication Sciences

Handout 7 Homework 6. Signal Processing for Communications March 30, 2009

PROBLEM 1 (PROBLEM 5.6 IN THE BOOK). Consider the following input-output relations and, for each of the underlying systems, determine whether the system is linear, time invariant, BIBO stable, causal or anti-causal. Characterize the eventual LTI systems by their impulse response.

- $\bullet \ y[n] = x[-n].$
- $y[n] = e^{-jwn}x[n]$ .
- $y[n] = \sum_{k=n-n_0}^{n+n_0} x[k]$ .
- y[n] = ny[n-1] + x[n] such that if x[n] = 0 for  $n < n_0$ , then y[n] = 0 for  $n < n_0$ .

PROBLEM 2 (PROBLEM 5.7 IN THE BOOK). Derive the impulse response of a bandpass filter with center frequency  $\omega_0$  and passband  $\omega_b$ :

$$H_{bp}(e^{jw}) = \begin{cases} 1 & \omega_0 - \omega_b \le \omega \le \omega_0 + \omega_b, \\ 1 & -\omega_0 - \omega_b \ge \omega \ge -\omega_0 + \omega_b, \\ 0 & \text{elsewhere.} \end{cases}$$

(Hint: Consider the following ingredients: a cosine of frequency  $\omega_0$ , a lowpass filter of bandwidth  $\omega_b$  and the modulation theorem.)

PROBLEM 3. For each of the following sequences x[n], find the z-transform X(z) and the corresponding region of convergence, and sketch the pole-zero diagram.

- $x[n] = \delta[n-3] + \delta[n+3]$
- $\bullet \ x[n] = na^n u[n]$
- $\bullet \ x[n] = -na^n u[-n-1]$
- $x[n] = 2^n u[n] 3^n u[-n-1]$
- $x[n] = e^{n^4} \left[\cos(\frac{\pi}{12}n)\right] u[n] e^{n^4} \left[\cos(\frac{\pi}{12}n)\right] u[n-1]$

PROBLEM 4. An LTI system is described by the difference equation

$$y[n] = \frac{9}{2}y[n-1] + \frac{5}{2}y[n-2] + x[n-1] + x[n]$$

- (i). Find the system response H(z) = Y(z)/X(z), and plot its pole-zero diagram.
- (ii). Find the region of convergence of H(z) when the system is
  - anticausal, unstable.
  - causal, unstable.
  - causal, stable.

- noncausal, stable.
- Find the impulse response h[n] of each of the above systems.

PROBLEM 5 (PROBLEM 5.36 IN OPPENHEIM, SCHAFER, BUCK). A causal linear time-invarient system has the system function

$$H(z) = \frac{(1 - 1.5z^{-1} - z^{-2})(1 + 0.9z^{-1})}{(1 - z^{-1})(1 + 0.7jz^{-1})(1 - 0.7jz^{-1})}$$

- 1. Write the difference equation that is satisfied by the input and the output of the system.
- 2. Plot the pole-zero diagram and indicate the region of convergence for the system function.
- 3. State whether the following are true or false about the system:
  - The system is stable.
  - The impulse response approaches a constant for large n.
  - The system has a stable and causal inverse.