ÉCOLE POLYTECHNIQUE FÉDÉRALE DE LAUSANNE

School of Computer and Communication Sciences

Handout 6	Signal Processing for Communications
Homework 5.	March 23, 2009

PROBLEM 1 (PROBLEM 5.1 IN THE BOOK). Consider the transformation $\mathcal{H}\{x[n]\} = nx[n]$. Does \mathcal{H} define an LTI system?

PROBLEM 2 (PROBLEM 5.2 IN THE BOOK). Consider a discrete-time system $\mathcal{H}\{\cdot\}$. When the input is the signal $x[n] = \cos((2\pi/5)n)$, the output is $\mathcal{H}\{x[n]\} = \sin((\pi/2)n)$. Can the system be linear and time-invariant? Explain.

PROBLEM 3 (PROBLEM 5.3 IN THE BOOK). Consider the finite-support signal h[n] defined as

$$h[n] = \begin{cases} 1 & \text{for } |n| \le M\\ 0 & \text{otherwise} \end{cases}$$

- 1. Compute the signal x[n] = h[n] * h[n] for M = 2 and sketch the result.
- 2. Compute the DTFT of x[n], $X(e^{j\omega})$, and sketch its value in the interval $[0, \pi]$.
- 3. Give a qualitative description of how $|X(e^{j\omega})|$ changes as M grows.
- 4. Compute the signal y[n] = x[n] * h[n] for M = 2 and sketch the result. For a general M, is the behavior of the sequence y[n]? (E.g. is it linear in n? Is it quadratic?)
- 5. Compute $Y(e^{j\omega})$ and sketch its value.

PROBLEM 4. Let x[n] be a discrete-time sequence defined as

$$x[n] = \begin{cases} M-n & 0 \le n \le M\\ M+n & -M \le n \le 0\\ 0 & \text{otherwise} \end{cases}$$

for some odd integer M.

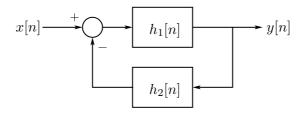
- 1. Show that x[n] can be expressed as the convolution of two discrete-time sequences $x_1[n]$ and $x_2[n]$.
- 2. Using the previous results, compute the DTFT of x[n].

PROBLEM 5. Consider the feedback connection of two linear, time-invariant, discrete-time sysystems as shown in the figure. Given that

$$h_1[n] = \delta[n]$$

$$h_2[n] = (-2)^n u[n-1]$$

determine the impulse response h[n] of the interconnected system. Are the systems represented by $h_1[n]$ and $h_2[n]$ stable? Is the overall system stable? Is it causal? Same question with $h_2[n] = (-2)^{n-1}u[n-1]$.



PROBLEM 6. Consider the cascade connection of two LTI systems. The system is characterized as follows:

$$H_1(e^{j\omega}) = \begin{cases} 1, & |w| < 0.5\pi \\ 0 & 0.5\pi \le |\omega| < \pi. \end{cases}$$
$$y[n] = w[n] - w[n-1]$$

Determine the output y[n] when $x[n] = \cos(0.6\pi n) + 3\delta[n-5] + 2$. (Hint: Plotting the spectrums of the signals and the impulse responses might help).

$$x[n] \longrightarrow h_1[n] \qquad w[n] \qquad h_2[n] \qquad y[n]$$