

# ÉCOLE POLYTECHNIQUE FÉDÉRALE DE LAUSANNE

School of Computer and Communication Sciences

## Handout 4

Introduction to Communication Systems

Solutions to Homework 2

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PROBLEM 1. (a) The system is not causal, because the output has a non-zero value at  $n = -1$ , which means that we get an output even before we have applied the input.

(b) The system is not linear, because if we add  $x_1 + x_2$  we get  $x_3$ , but  $y_3 \neq y_1 + y_2$ .

(c) We cannot say whether the system is time-invariant or not from the three test signals.

PROBLEM 2. From the definition of stability we know that if

$$\sum_{m=-\infty}^{\infty} |h(m)| < \infty$$

then the system is stable. So for the first case we know that the sum  $\sum_{m=0}^{\infty} \frac{1}{m}$  diverges, hence the system is unstable. Consider the input  $x[n] = u[n]$ , where

$$u[n] = \begin{cases} 1, & n \geq 0 \\ 0, & \text{else} \end{cases}$$

The output of the system is

$$y[n] = \sum_{m=0}^{n-1} \frac{1}{n-m}$$

Clearly as  $n$  increases we cannot bound the output  $y[n]$  with a constant even though the input is always 1.

The second system is stable because the sum

$$\sum_{m=0}^{\infty} \frac{1}{m^2} = \frac{\pi^2}{6}$$

converges to a constant. So for any input which is bounded by a constant over all the range of time, the output will also be bounded by a constant.

PROBLEM 3. (a)  $x(n)$

(b)  $x(n+3)$  is  $x(n)$  shifted by 3 to the left

$$(c) x(2-n)\delta(n-1) = \begin{cases} x(1) & \text{if } n = 1 \\ 0 & \text{otherwise} \end{cases} .$$

(d)  $x(n-1)$  is  $x(n)$  shifted by 1 to the right and the convolution with  $\delta(3-n)$  shifts the signal by 3 to the right. So  $x(n-1) \star \delta(3-n)$  is  $x(n)$  shifted by 4 to the right.

PROBLEM 4. (a) the output is given by  $h(-1) = 1$ ,  $h(0) = 3.25$ ,  $h(1) = 2.5$ ,  $h(2) = 2$ ,  $h(3) = 3.5$ ,  $h(4) = 1.25$

(b) the impulse response is  $h(n) = h_1(n) \star h_2(n)$ . It is the same if we swap  $H_1$  and  $H_2$  since the convolution is a commutative operator.

This system is also a filter, since we can see that:

- It is linear (we can easily prove that the cascade of two linear systems is also linear)
- It is time invariant (the composition of two invariant systems is also time invariant)
- The domain of the input and output signals is the same (in this case it is  $\mathbb{Z}$ )

PROBLEM 5. 1. (a)  $x[n] = \text{Im}(e^{j\omega n})$

(b)  $\text{Im}(\gamma a + \beta b) = \text{Im}(\gamma x + j\gamma y + \beta u + j\beta v)$  where  $a = x + jy$ ,  $b = u + jv$  and  $\gamma, \beta \in \mathbb{R}$ . Thus

$$\begin{aligned}\text{Im}(\gamma a + \beta b) &= \gamma y + \beta v \\ &= \gamma \text{Im}(a) + \beta \text{Im}(b)\end{aligned}$$

(c) Let the input be  $x[n] = e^{j\omega n}$ . Convolution gives us

$$\begin{aligned}y[n] &= \sum_{m=-\infty}^{\infty} e^{j\omega(n-m)} h(m) \\ &= \sum_{m=0}^{\infty} e^{j\omega(n-m)} \alpha^m \\ &= e^{j\omega n} \sum_{m=0}^{\infty} (e^{-j\omega} \alpha)^m \\ &= e^{j\omega n} \frac{1}{1 - e^{-j\omega} \alpha}\end{aligned}$$

Thus the amplitude of the output is given by

$$\begin{aligned}\left| \frac{1}{1 - e^{-j\omega} \alpha} \right| &= \left| \frac{1}{1 - \alpha \cos \omega + j\alpha \sin \omega} \right| \\ &= \left| \frac{1 - \alpha \cos \omega - j\alpha \sin \omega}{(1 - \alpha \cos \omega)^2 + (\alpha \sin \omega)^2} \right| \\ &= \frac{1}{\sqrt{(1 - \alpha \cos \omega)^2 + (\alpha \sin \omega)^2}}\end{aligned}$$

Thus the output is given by

$$y[n] = \frac{1}{\sqrt{(1 - \alpha \cos \omega)^2 + (\alpha \sin \omega)^2}} e^{j(\omega n + \phi)}$$

where

$$\tan \phi = \frac{-\alpha \sin \omega}{1 - \alpha \cos \omega}$$

(d) The input signal is  $\text{Im}(e^{j\omega n})$ . Thus the output is given by

$$\begin{aligned}y[n] &= \sum_{m=-\infty}^{\infty} \text{Im}(e^{j\omega(n-m)}) h(m) \\ &= \text{Im} \left( \sum_{m=-\infty}^{\infty} e^{j\omega(n-m)} h(m) \right) \\ &= \text{Im} \left( \sum_{m=0}^{\infty} e^{j\omega(n-m)} h(m) \right)\end{aligned}$$

The second equality follows from the linearity of the  $\text{Im}(\cdot)$  function. Using the solution to the part above we get

$$\begin{aligned} y[n] &= \text{Im}\left(\frac{1}{\sqrt{(1 - \alpha \cos \omega)^2 + (\alpha \sin \omega)^2}} e^{j(\omega n + \phi)}\right) \\ &= \frac{1}{\sqrt{(1 - \alpha \cos \omega)^2 + (\alpha \sin \omega)^2}} \sin(\omega n + \phi) \end{aligned}$$

where  $\phi$  is given in the solution to the previous part.

2. The amplitude is given by

$$\frac{1}{\sqrt{(1 - \alpha \cos \omega)^2 + (\alpha \sin \omega)^2}}$$

For  $\omega = 0$  the amplitude is  $\frac{1}{1-\alpha}$ . For  $\omega = \pi$  the amplitude is  $\frac{1}{1+\alpha}$ .

3. As  $\alpha \rightarrow 1$  the amplitude at  $\omega = 0$  tends to infinity and amplitude at  $\omega = \pi$  tends to  $\frac{1}{2}$ . This is a like a low-pass filter.